

LOFAR Retrospective Analysis

Analyzing LOFAR station processing

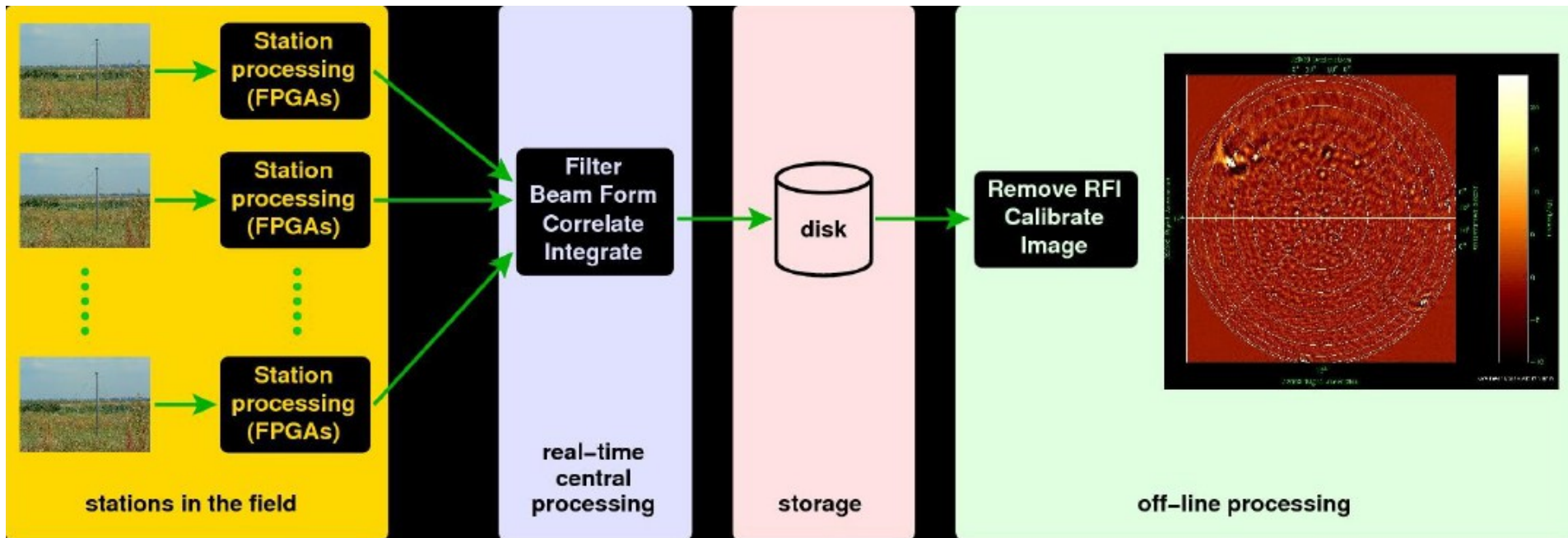


Retrospective analysis goals

- Understand **compute and bandwidth distribution** for sky imaging
- How do these properties relate to the **required compute system**?
 - Architecture
 - System size
 - Energy usage
- Use LOFAR as a basis to determine models and scaling rules
- Apply the results of the LOFAR retrospective analysis to the SKA



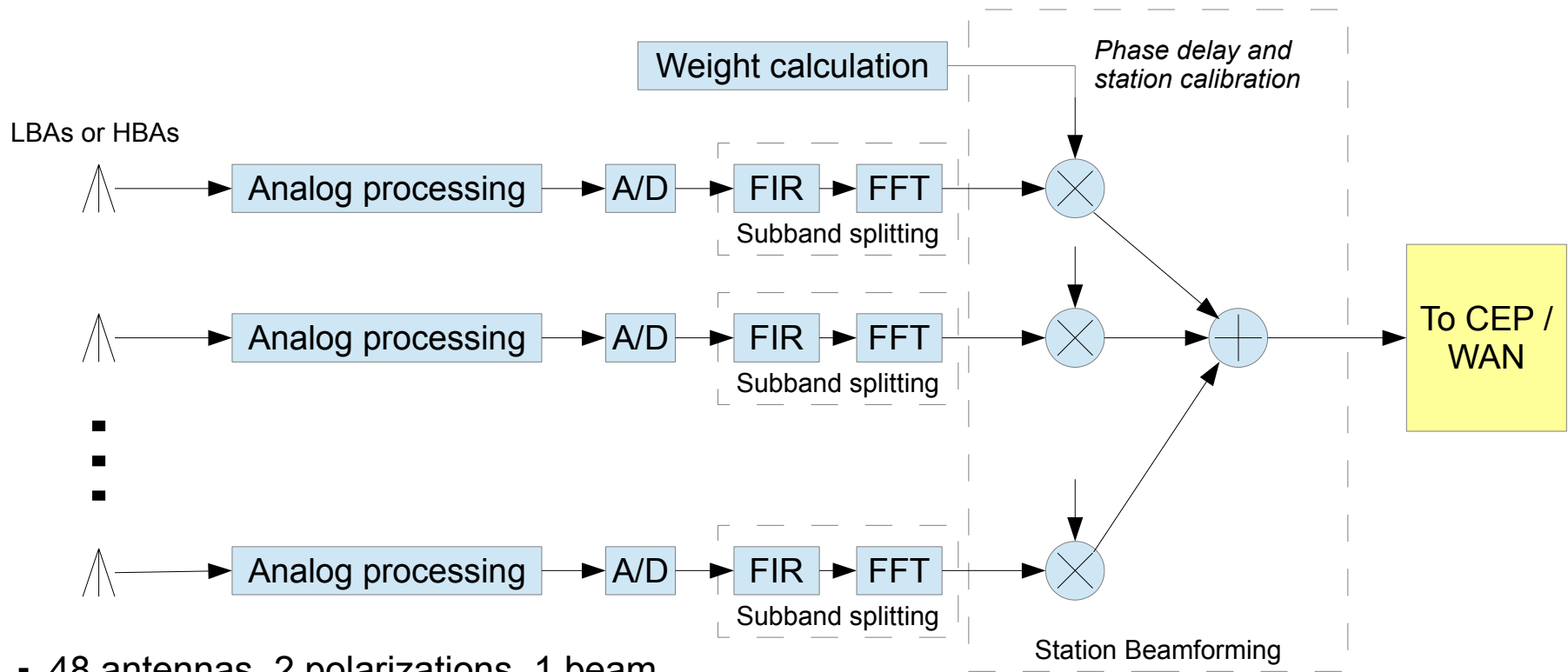
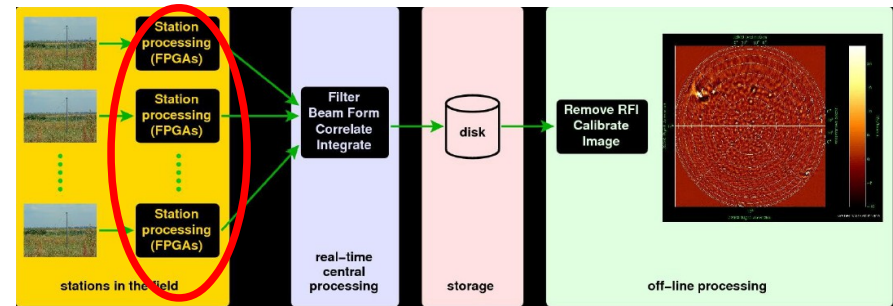
Content



Source: John Romein

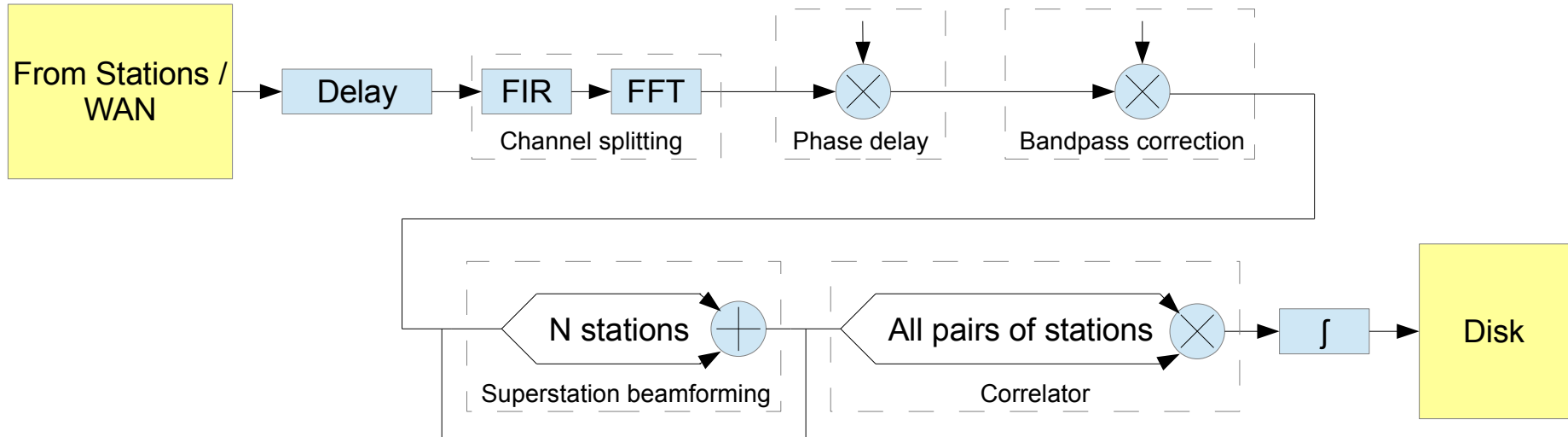
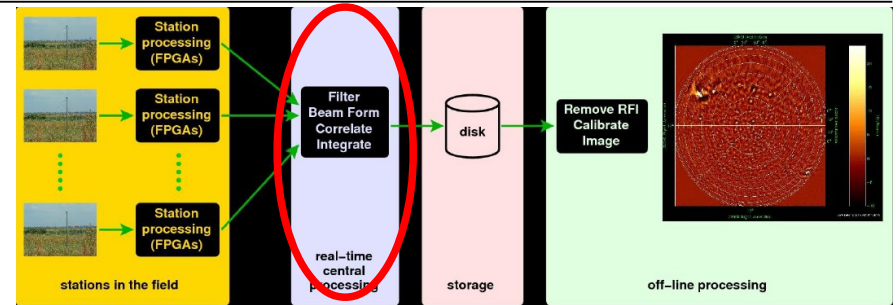
- Focus on station and central processing (correlator)
 - Basis to extend the analysis to post-correlator imaging
- Determine computational and bandwidth **scaling rules** for LOFAR digital signal path
- Analysis of **station processing on modern parallel platforms**
 - System size requirements
 - Energy consumption

LOFAR station processing



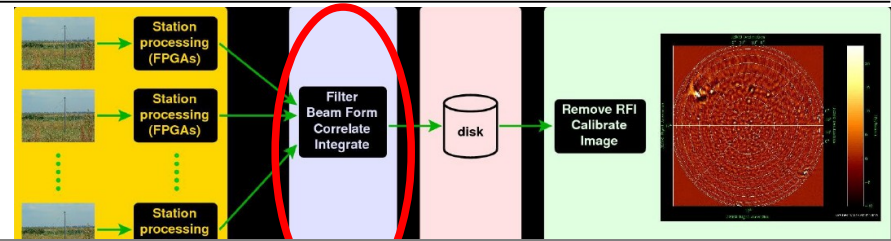
- 48 antennas, 2 polarizations, 1 beam
- 248/512 subbands beamformed

LOFAR central processing

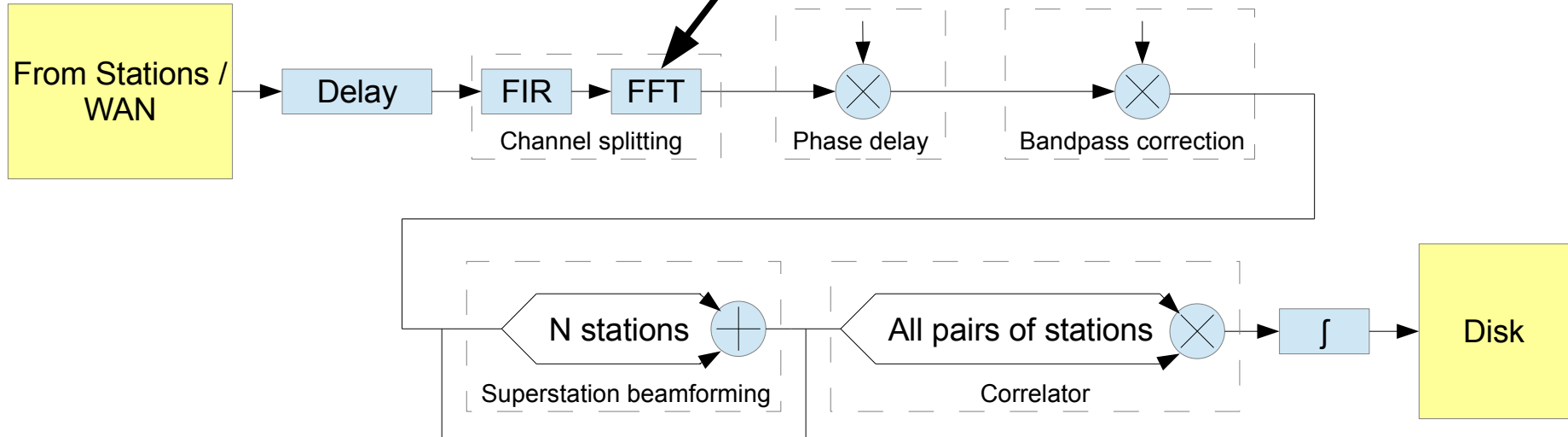


- 64 stations, 2 polarizations, 1 beam
- Channel splitting: 256 channels

LOFAR central processing

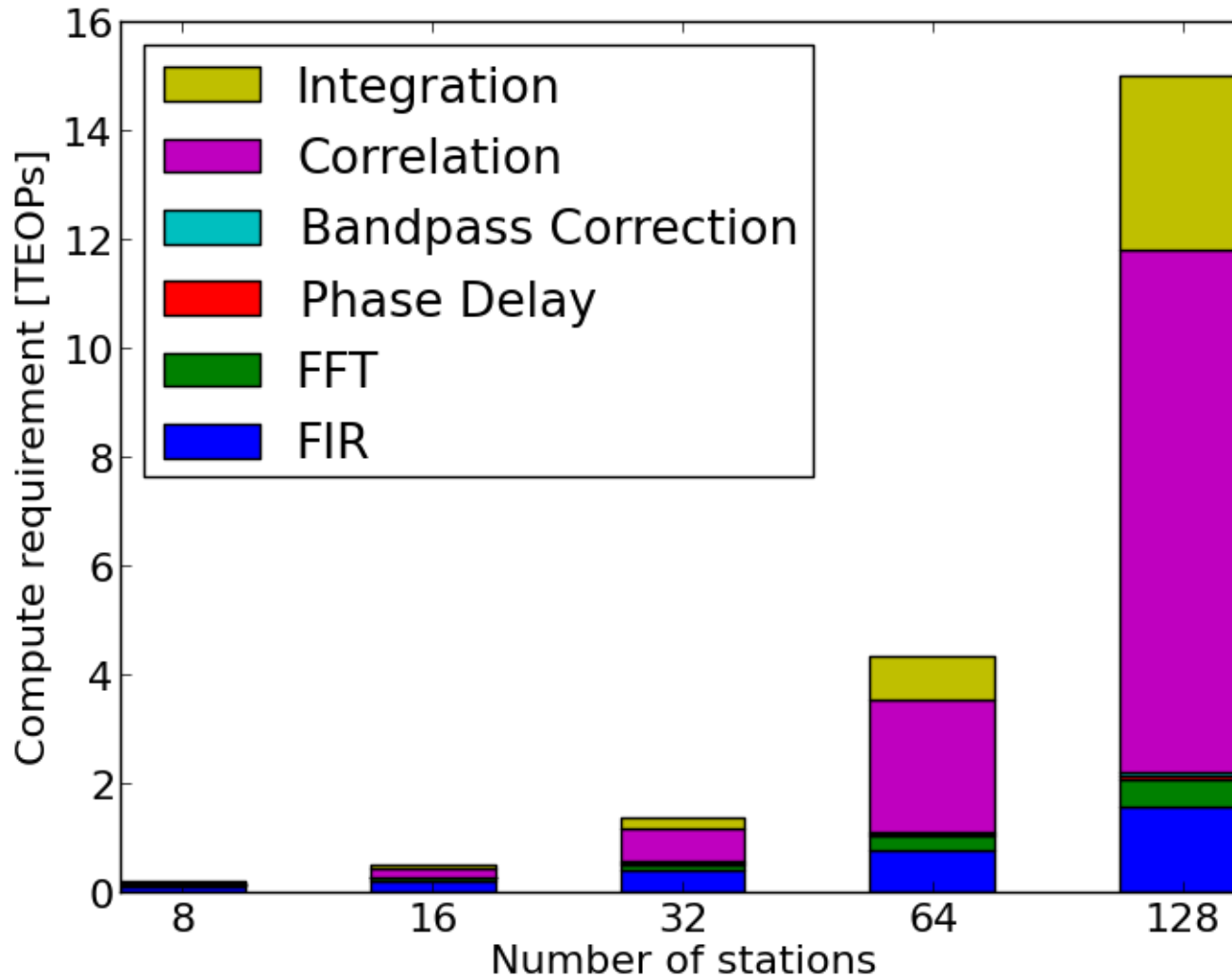


$$N_{ops} = N_{stations} N_{beams} N_{subbands} N_{polarizations} 5 N_{points} \log_2 (N_{points})$$



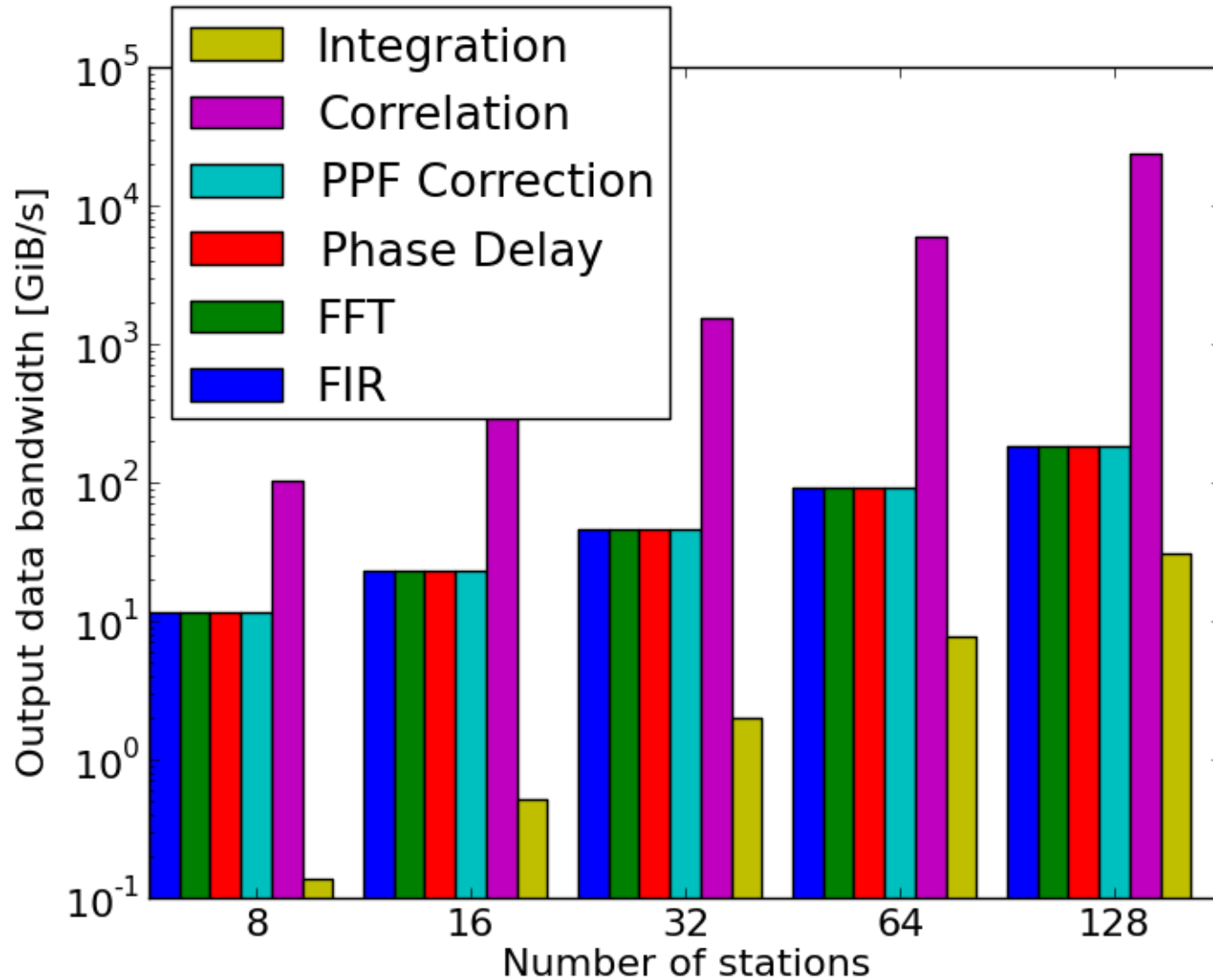
- 64 stations, 2 polarizations, 1 beam
- Channel splitting: 256 channels

Central processing compute scales quadratically

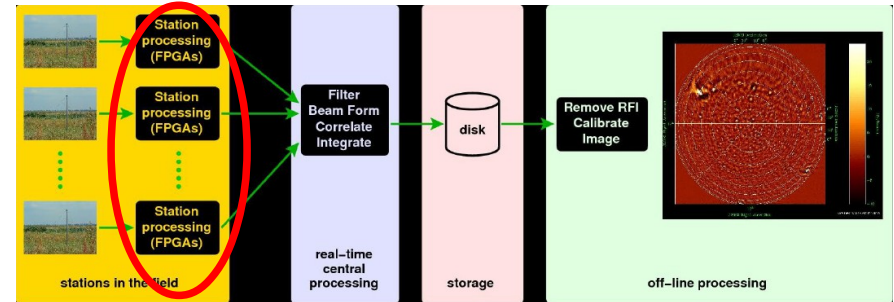


- TEOPS = Tera Effective Operations per second

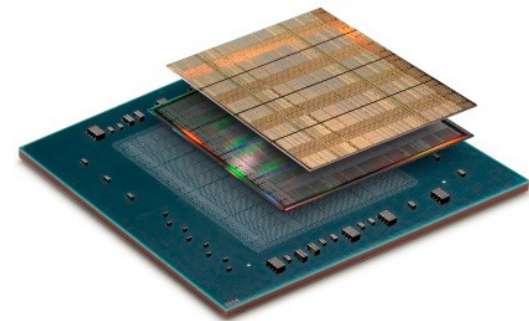
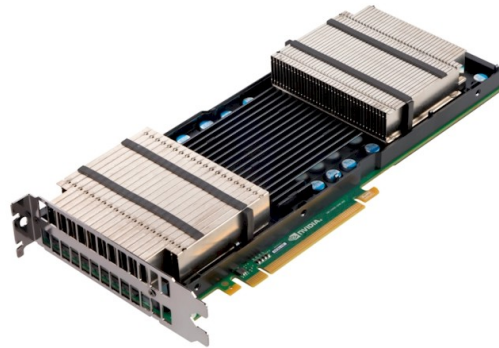
Central processing data reduction by integration



LOFAR station processing on parallel platforms



- Behavior of station processing on **modern, parallel platforms**



- Roofline analysis to extrapolate to full station size
- How would we design LOFAR station processing, giving modern technologies?*

Fixed-point versus floating-point

- FPGA best performance with **fixed-point arithmetic**
- CPU and GPU best performance with **floating-point arithmetic**
 - Keep integer data path for bookkeeping (e.g. address calculations)
- Fixed-point implementation is more tedious
- 32-bit Floating-point arithmetic has **no impact on accuracy** of station processing
- ***Choose best arithmetic type for each platform***

Station processing: low computational intensity

Block	Parameter	Requirement (32-bit FP)
FIR	Compute	595.2 GFLOPs
	Antenna data in	71.5 GB/s
	FIR data out	71.5 GB/s
	Coefficients, delayed samples in/out	2.27 TB/s
	Computational intensity	0.25 ops/byte
FFT	Compute	480 GFLOPs
	FIR data in	71.5 GB/s
	FFT data out	71.5 GB/s
	Twiddle factors	357.5 GB/s
	Computational intensity	1.1 ops/byte
BF	Compute	74.2 GFLOPs
	FFT data in	34.6 GB/s
	BF data out	739 MB/s
	Calibration data	138.6 GB/s
	Computational intensity	0.43 ops/byte
Total	Compute	1.1 TFLOPs
	Total data bandwidth	3.0 TB/s
	Computational intensity	0.4 ops/byte

- Operational intensity: 59.9 ops/sample

GPU cannot reach peak performance for station processing

Type	Platform	Introduction	Peak performance	Off-chip bandwidth
CPU	Quad-core Intel i7-3820	2012	230.4 GEOPs <i>Quad-core, AVX</i>	40 GB/s <i>40 lanes PCI-express 3.0</i>
GPU	Nvidia K10	2012	2 x 2288 GEOPs <i>Dual GK104</i>	16 GB/s <i>16 lanes PCI-express 3.0</i>
FPGA	Xilinx Virtex-4 SX35	2004	76.8 GEOPs <i>192 DSP slices</i>	11.2 GB/s <i>112 LVDS pairs</i>
FPGA	Xilinx Virtex-7 x690T	2010	1440 GEOPs <i>3600 DSP slices</i>	131 GB/s <i>80 GTH transceivers</i>

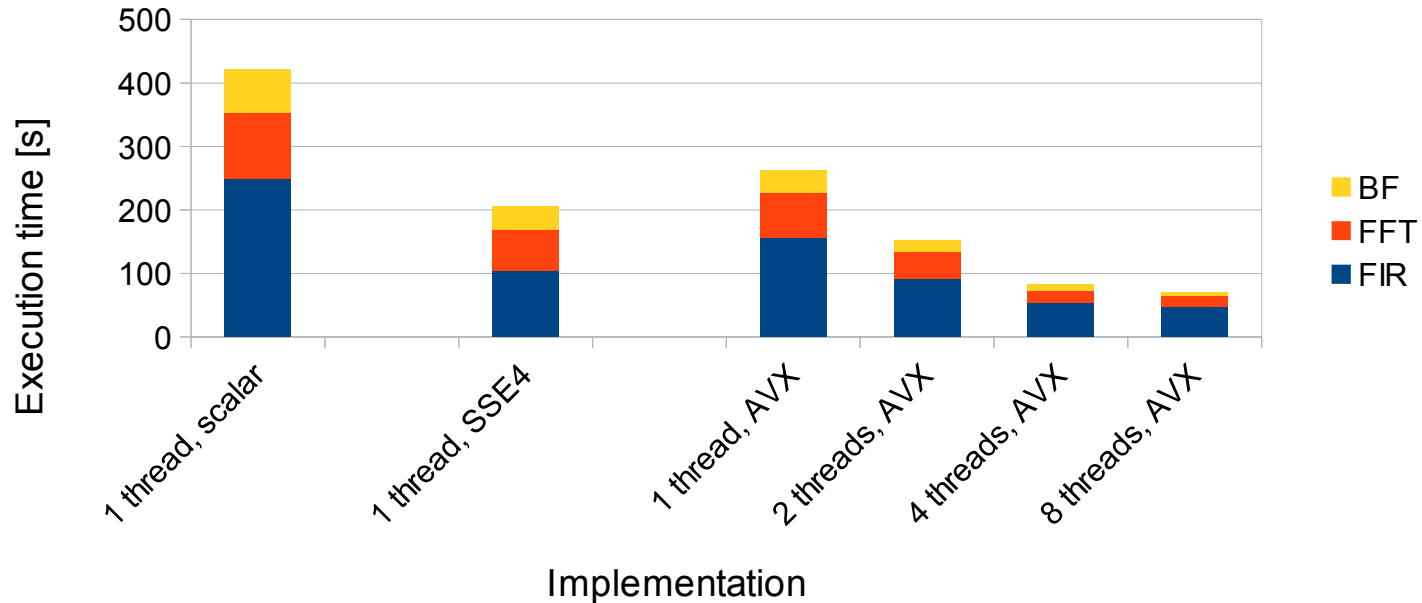
Type	Platform	Operational intensity	Required operational intensity	Max performance
CPU	Intel i7-3820	5.76 ops/byte	29.9 ops / byte (16 bit / sample)	100 %
GPU	Nvidia K10	286 ops/byte	29.9 ops / byte (16 bit / sample)	10.9 %
FPGA	Virtex-4 SX35	6.8 ops/byte	39.9 ops / byte (12 bit / sample)	100 %
FPGA	Virtex-7 x690T	11 ops/byte	39.9 ops / byte (12 bit / sample)	100 %

Single CPU performance 55.5x below real-time



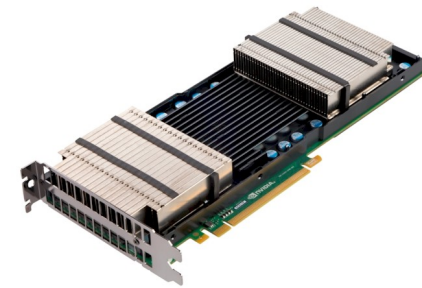
CPU performance of LOFAR station processing

Intel Core i7-3820, 1280 ms of antenna data



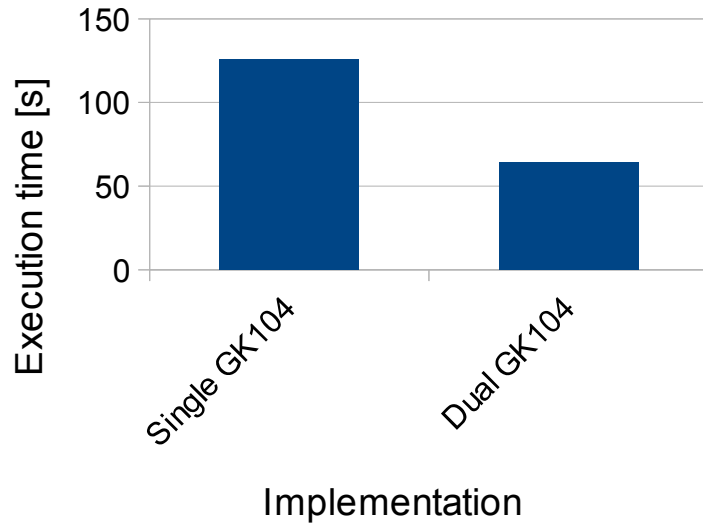
- Single-threaded AVX implementation worse compared to SSE4
 - Different vectorization strategy required for scaling to multiple threads*

GPU performance 6.1x below real-time



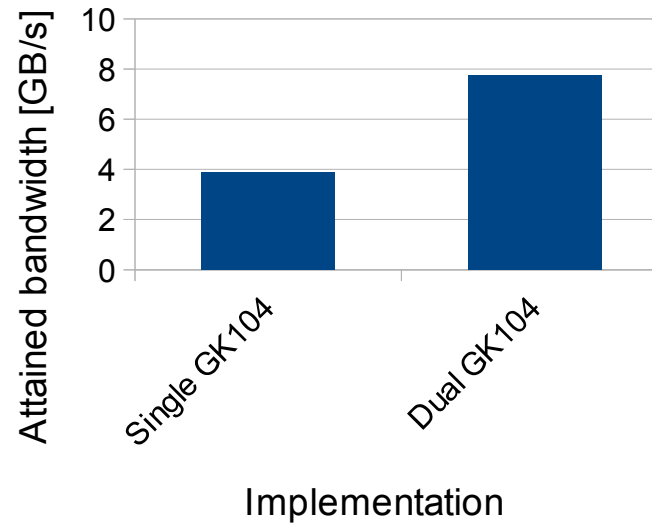
GPU performance of LOFAR station processing

Nvidia K10, 10240 ms of antenna data



Attained PCI-express bandwidth

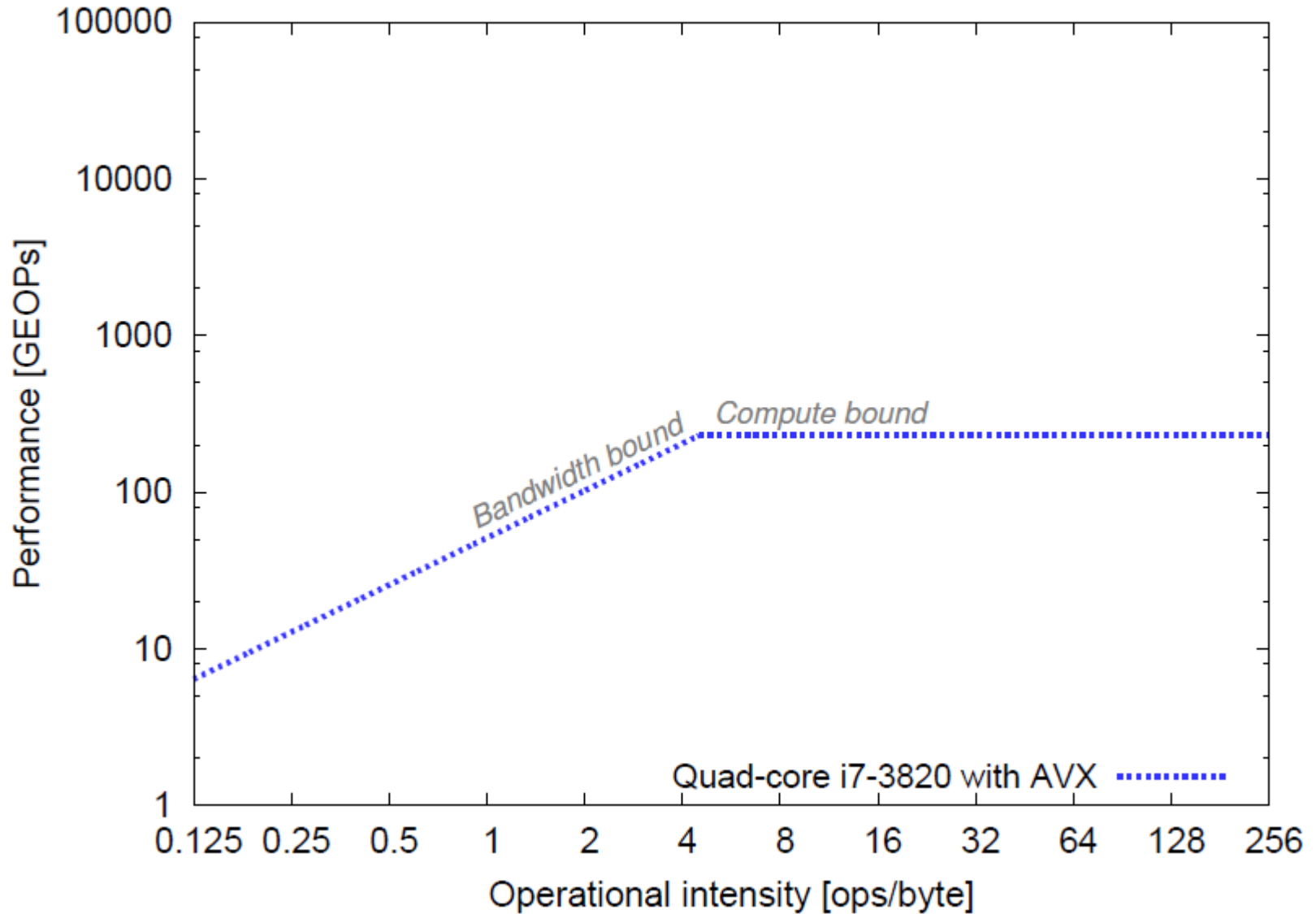
Nvidia K10



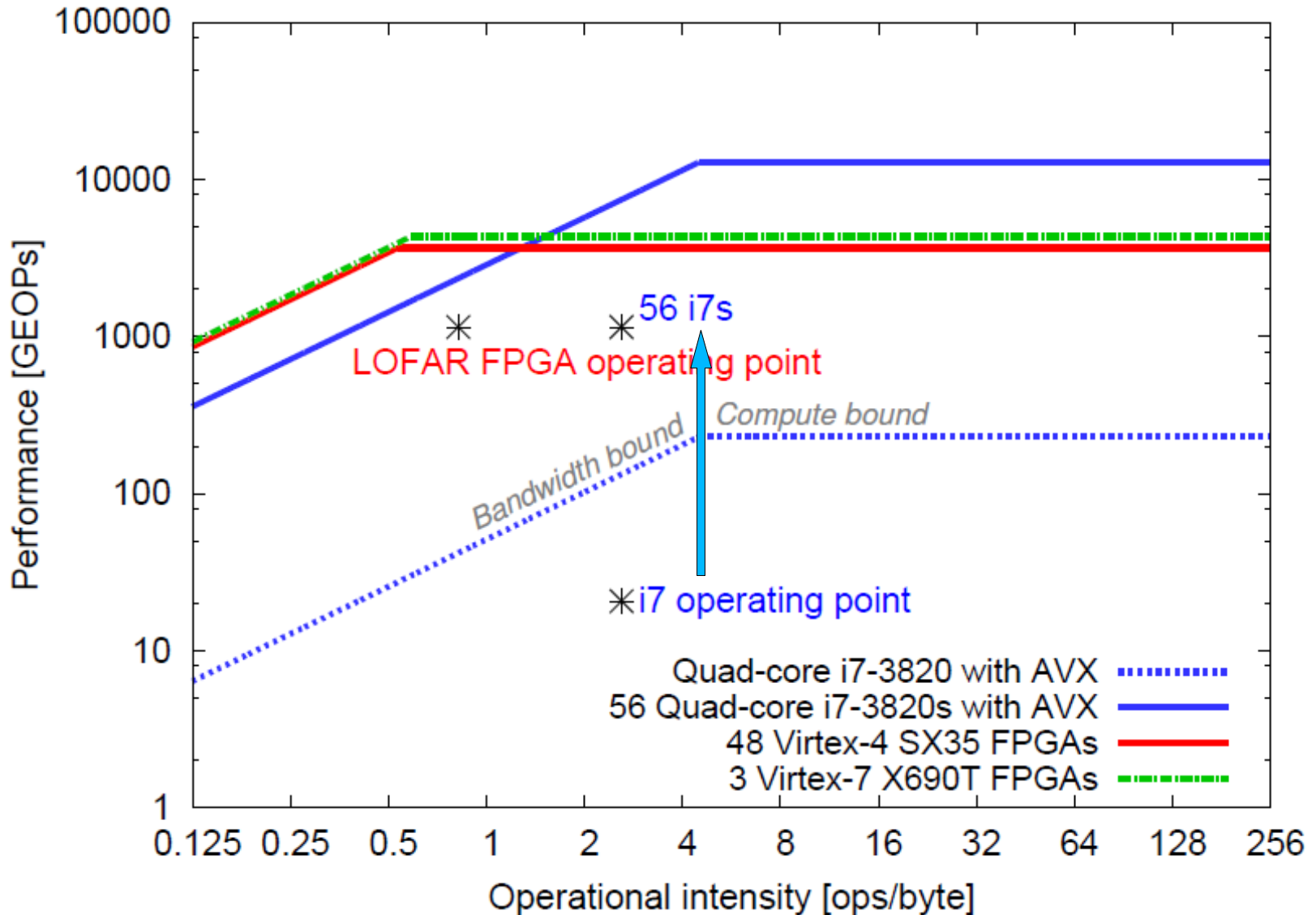
	GFLOPs	Reached % of peak performance	Theoretical max. % of peak performance
Single GK104	93.4	4.1 %	21.8 %
Dual GK104	183.2	4.0 %	10.9 %

- 8.8x improvement over Intel Core i7-3820 (8 threads, AVX)

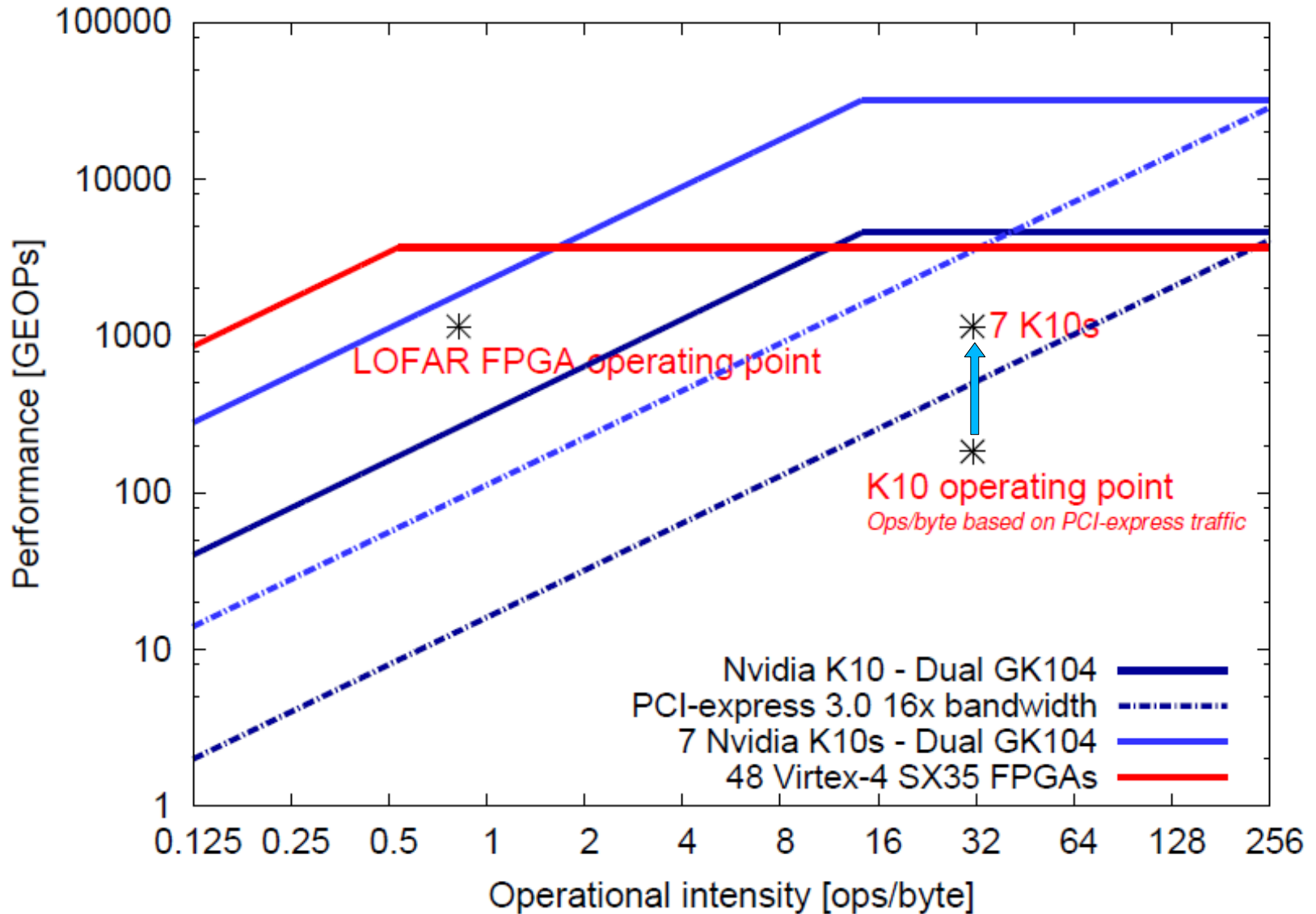
Roofline analysis



Roofline analysis: 3 Virtex-7s or 56 Intel Core i7s



Roofline analysis: 7 Nvidia K10s



Power measurement setup

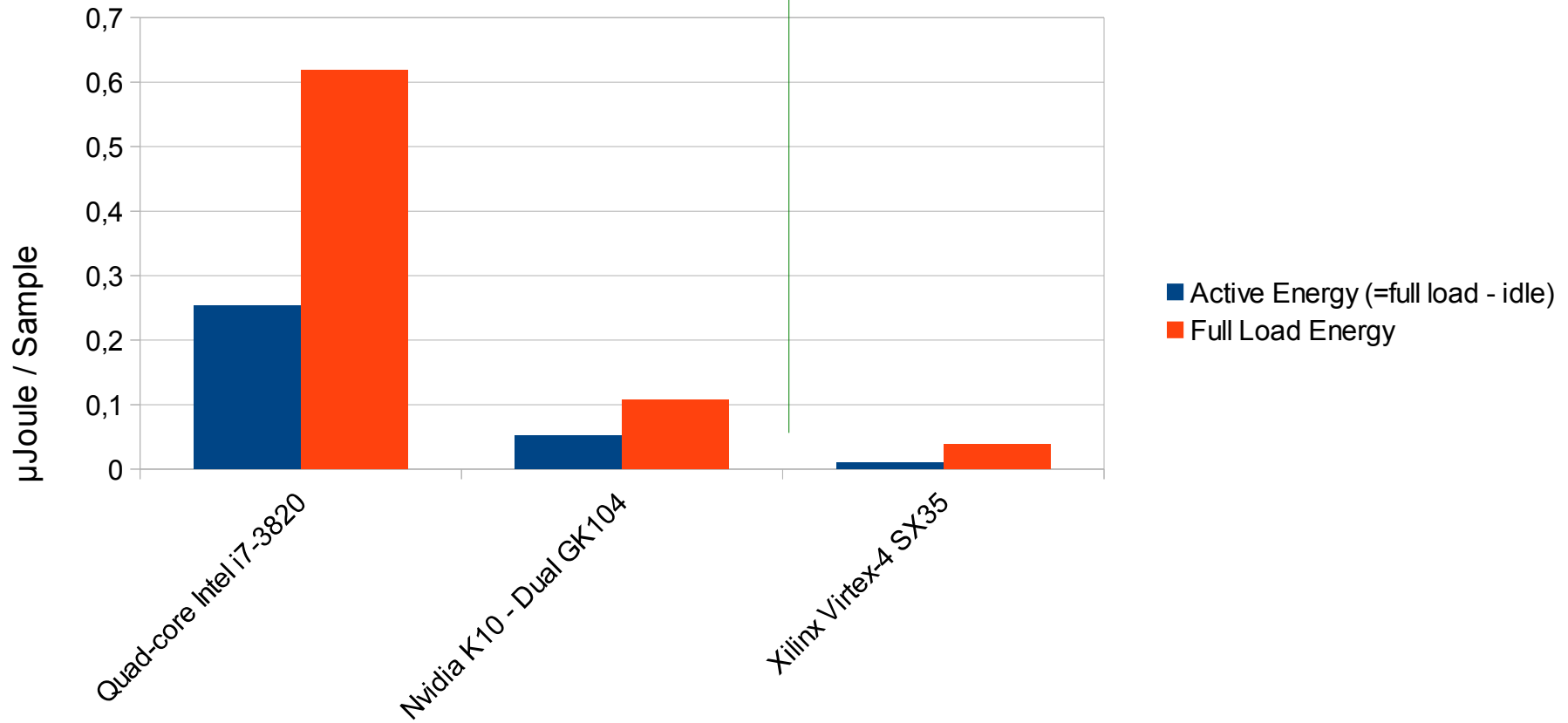
- Compare power consumption of complete system under full load
 - Favors FPGA implementation (no unused peripherals)
 - **Lower bound** on efficiency

- Compare power consumption of difference between full and idle load
 - Only compare active power
 - Does not include idle power of CPU/GPU/FPGAs
 - **Upper bound** on efficiency

FPGAs use least energy

Energy consumption of LOFAR station processing

Floating-point, 2012 | *Integer, 2004*



Conclusions

- Algorithms in station processing have low operational intensity
 - Impossible to reach peak performance on certain platforms
- Streaming data model and low operational intensity favor FPGAs
 - Relatively high off-chip bandwidth
- For station processing use FPGAs
 - Twice as many GPUs as FPGAs
 - FPGAs are ~5x more power efficient compared to GPUs
 - 2004 FPGA platform vs 2012 GPU
 - Integer arithmetic on FPGAs vs floating-point

Future work

- Extend analysis to post-correlation calibration and imaging
 - Determine scaling rules
 - Map results onto hardware platforms
- Algorithms expected to have higher operational intensity
 - Possible to get closer to peak performance on GPUs
 - GPUs expected to be (more) competitive with FPGAs
- Include ASICs and DSPs as a potential low-energy hardware platform

Questions?

Backup slides

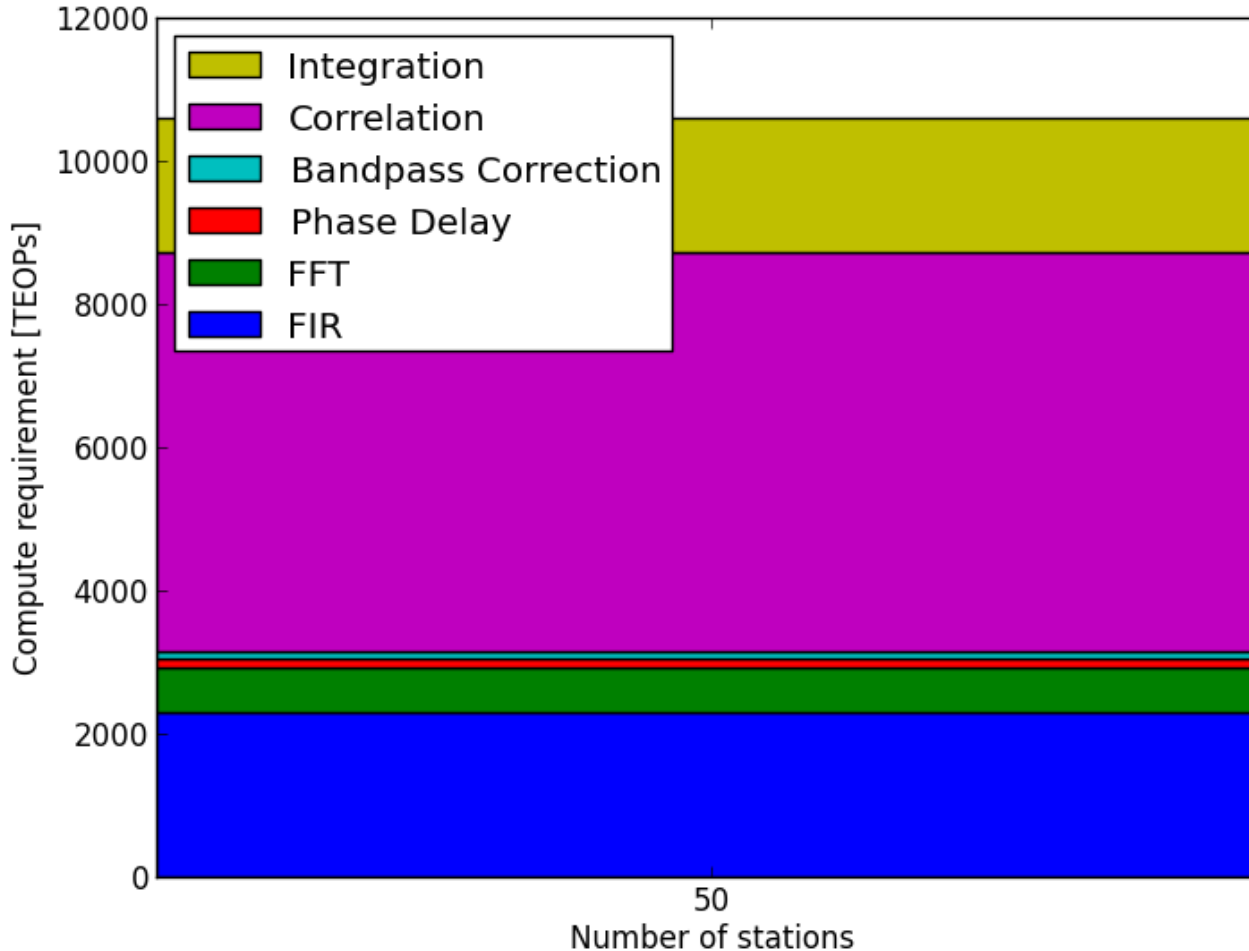
SKA phase 1 – Memo 130 [I]

- AA-Low
- 11.200 antennas/station, 50 stations
- 3040 subbands, 125 channels, 480 beams
- 380 MHz bandwidth

- Preliminary results

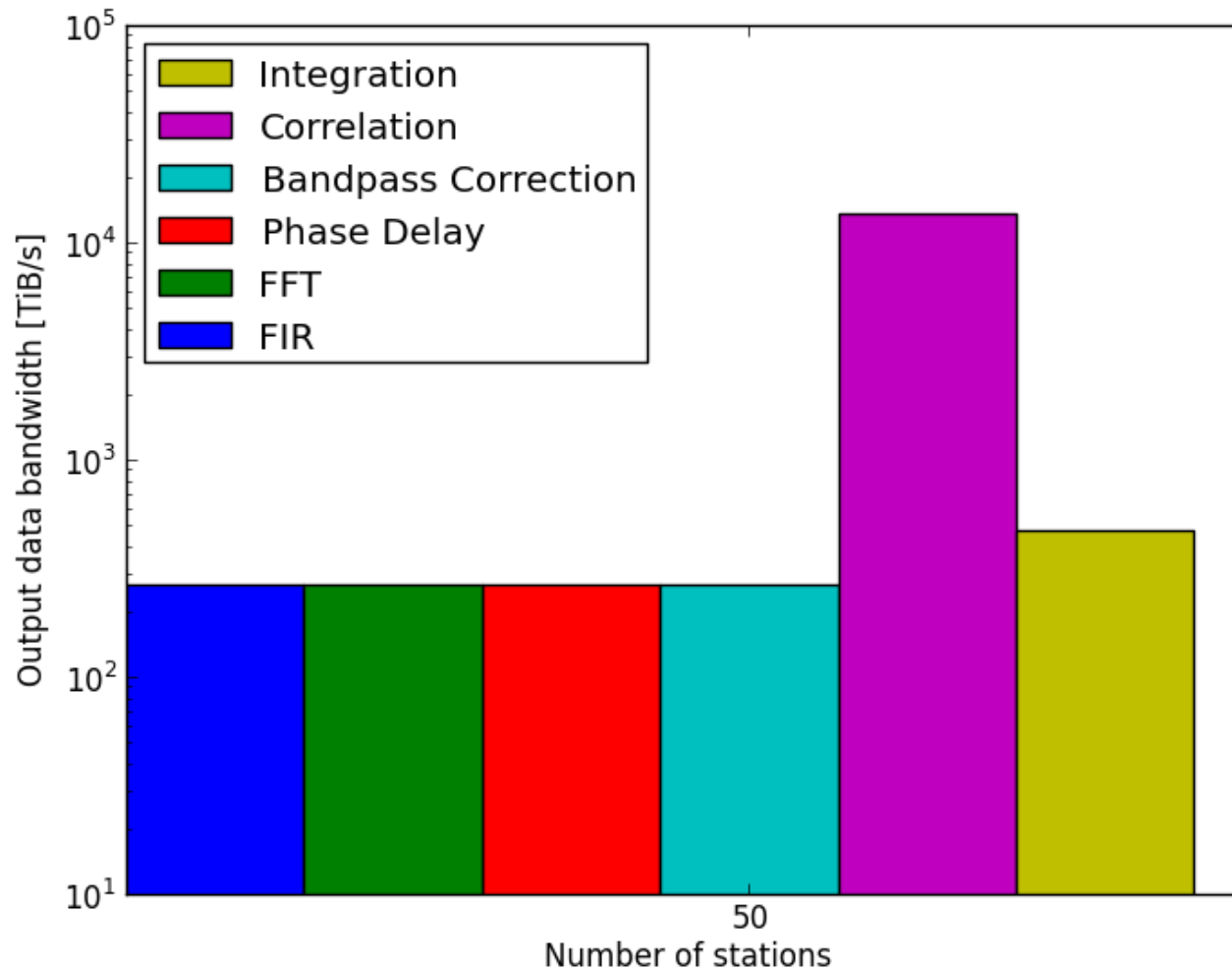
SKA phase 1 – Memo 130 [III]

- Central processor: compute (preliminary results)



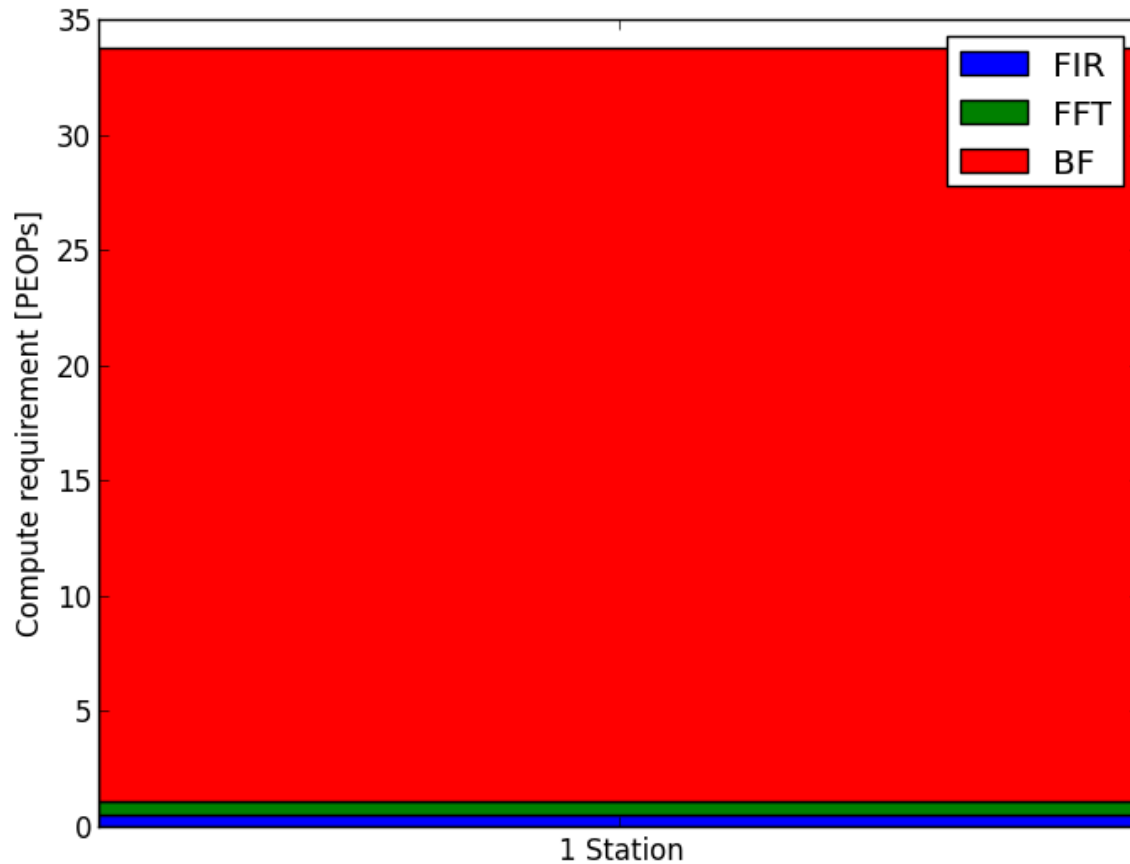
SKA phase 1 – Memo 130 [III]

- Central processor: data rates (preliminary results)



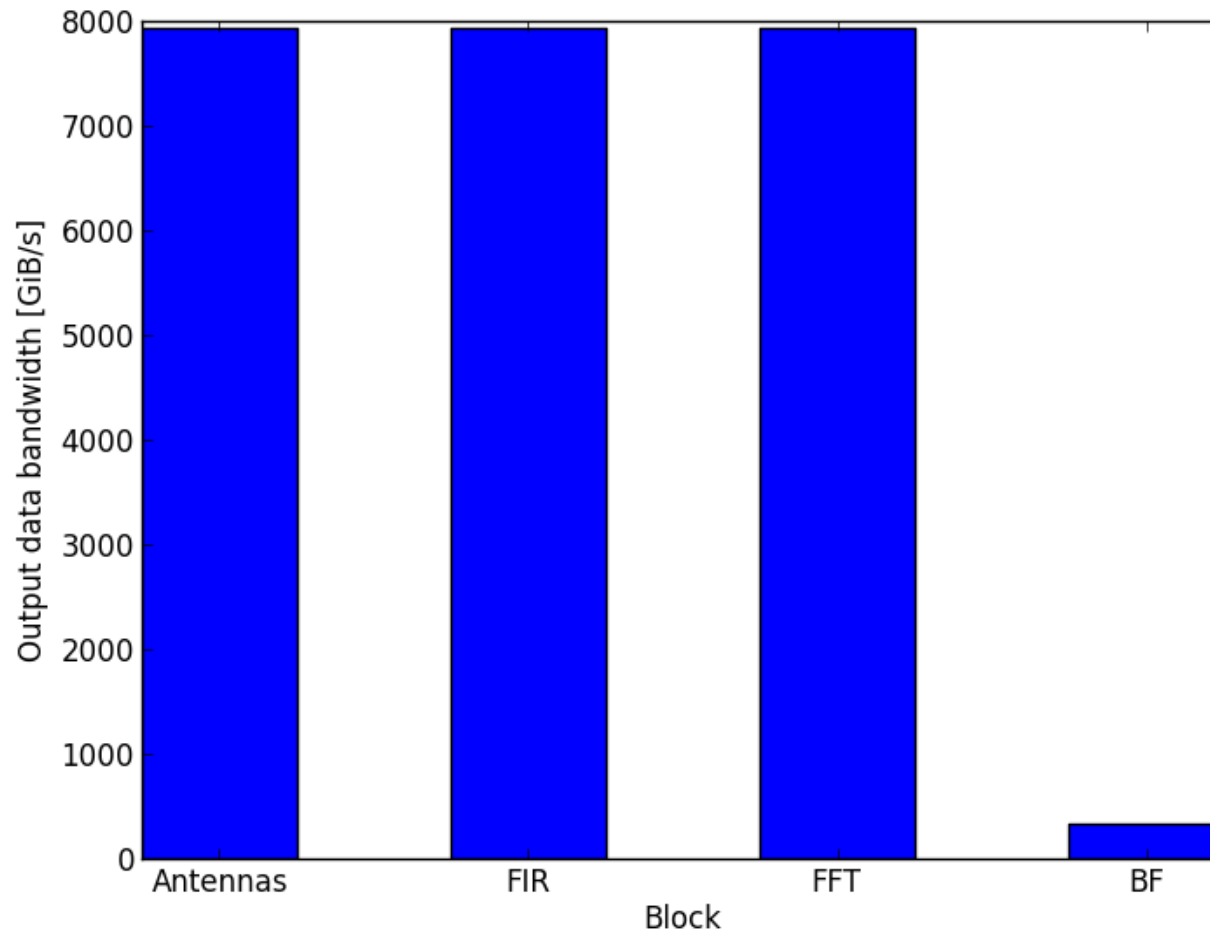
SKA phase 1 – Memo 130 [IV]

- Station processing: compute (preliminary results)



SKA phase 1 – Memo 130 [V]

- Station processing: data rates (preliminary results)



Platform selection — CPU

- Quad-core Intel Core i7-3820 @ 3.6 GHz
 - Launched Q1 2012
 - AVX extensions (256 bit- or 8 float-wide SIMD)
- Theoretical peak performance (quad-core , AVX)
 - 230.4 GFLOPs

	DDR3	PCI Express 3.0 40 lanes
Theoretical peak BW	51.2 GB/s	40 GB/s
Operational intensity	4.5 ops/byte	5.76 ops/byte

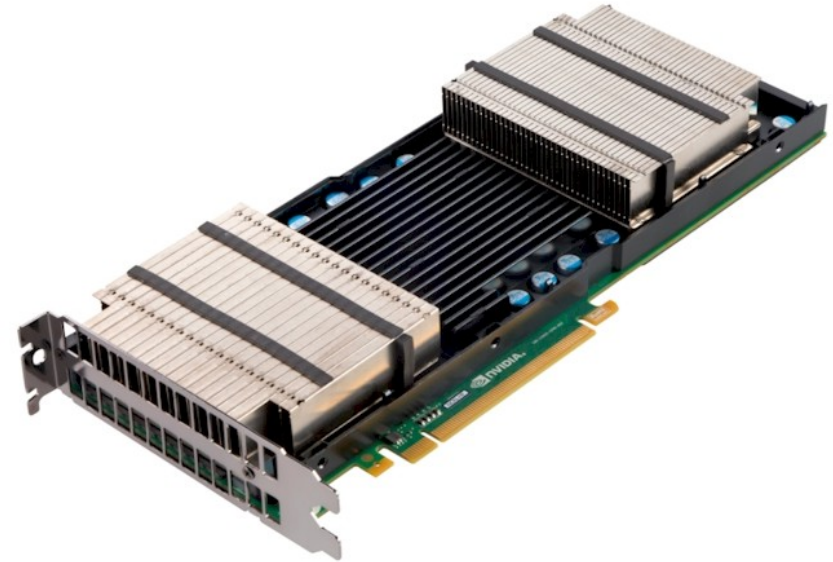


- For **32 bit / sample**: 15.0 ops/byte, BW sufficient to sustain peak performance

Platform selection — GPU

- Nvidia Tesla K10
 - Launched May 2012
 - Dual Kepler GK104 GPU

- Theoretical peak performance
 - 2288 GFLOPs per GPU

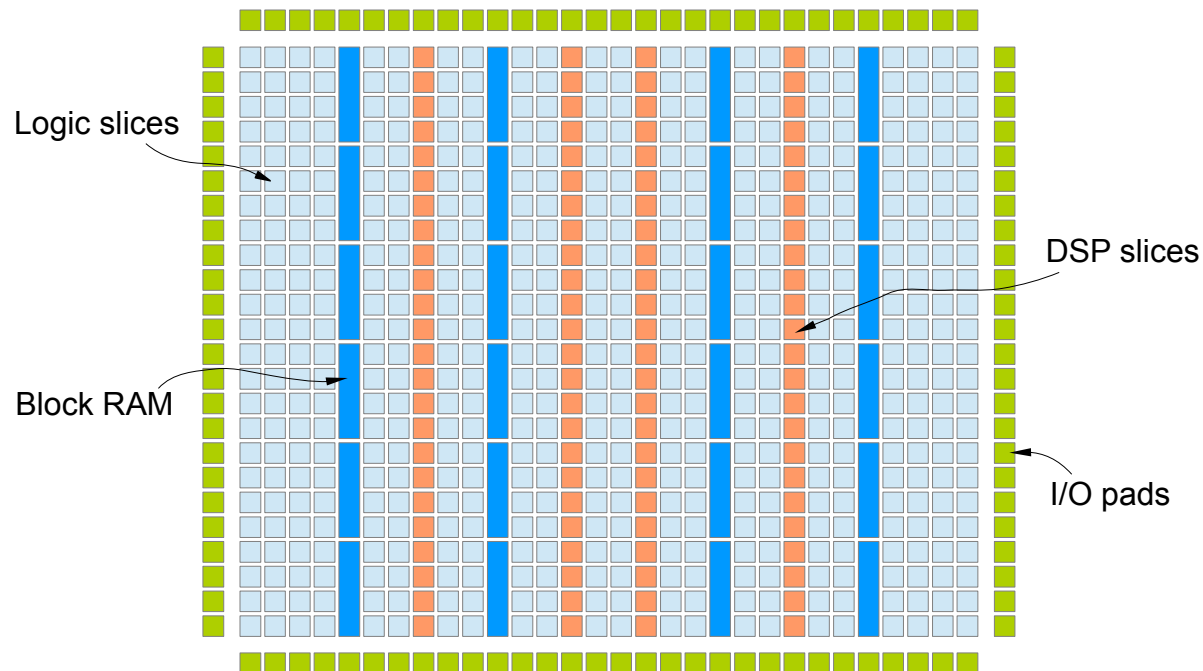


	GDDR5	PCI Express 3.0 16 lanes
Theoretical peak BW	160 GB/s	16 GB/s
Operational intensity	28.6 ops/byte	286 ops/byte

- For **16 bit / sample** over PCI-express:
 - 29.9 ops/byte for station processing: max. 10.9 % of peak performance

Platform selection — FPGA [I]

- Fixed-point performance: **giga effective operations per second** (GEOPs)
- Peak performance based on available DSP slices
- Peak memory bandwidth based on available block RAMs
 - Intermediate data fits in block RAMs for FPGA platforms used in the analysis



Platform selection — FPGA [III]

- In the field: Xilinx Virtex-4 SX35
 - Launched 2004
 - 192 DSP slices
 - 192 block RAMS
- Logic clocked @ 200 MHz
- Theoretical peak performance (DSP slices):
 - 76.8 GEOPs
- Theoretical peak memory bandwidth (block RAM):
 - 143 GB/s

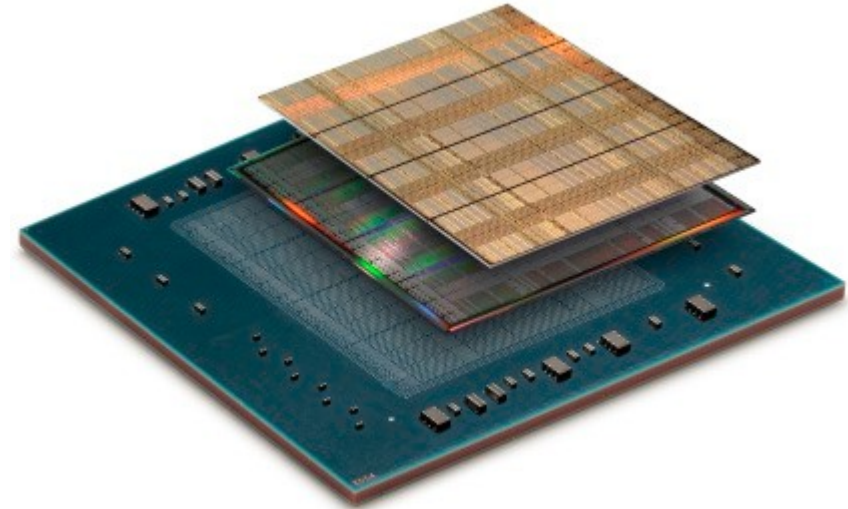
112 LVDS pairs

Theoretical peak BW	11.2 GB/s
Operational intensity	6.8 ops/byte

- For **12 bit / sample**: 39.9 ops/byte, BW sufficient

Platform selection — FPGA [III]

- Xilinx Virtex-7 x690T
 - Launched June 2010
 - 3600 DSP slices
 - 2940 block RAMS
- Assume logic clocked @ 200 MHz
- Theoretical peak performance (DSP slices):
 - 1440 GEOPs
- Theoretical peak memory bandwidth (block RAM):
 - 2352 TB/s



80 GTH transceivers

Theoretical peak BW	131 GB/s
Operational intensity	11 ops/byte

- For **12 bit / sample**: 39.9 ops/byte, BW sufficient

LOFAR station processing requirements

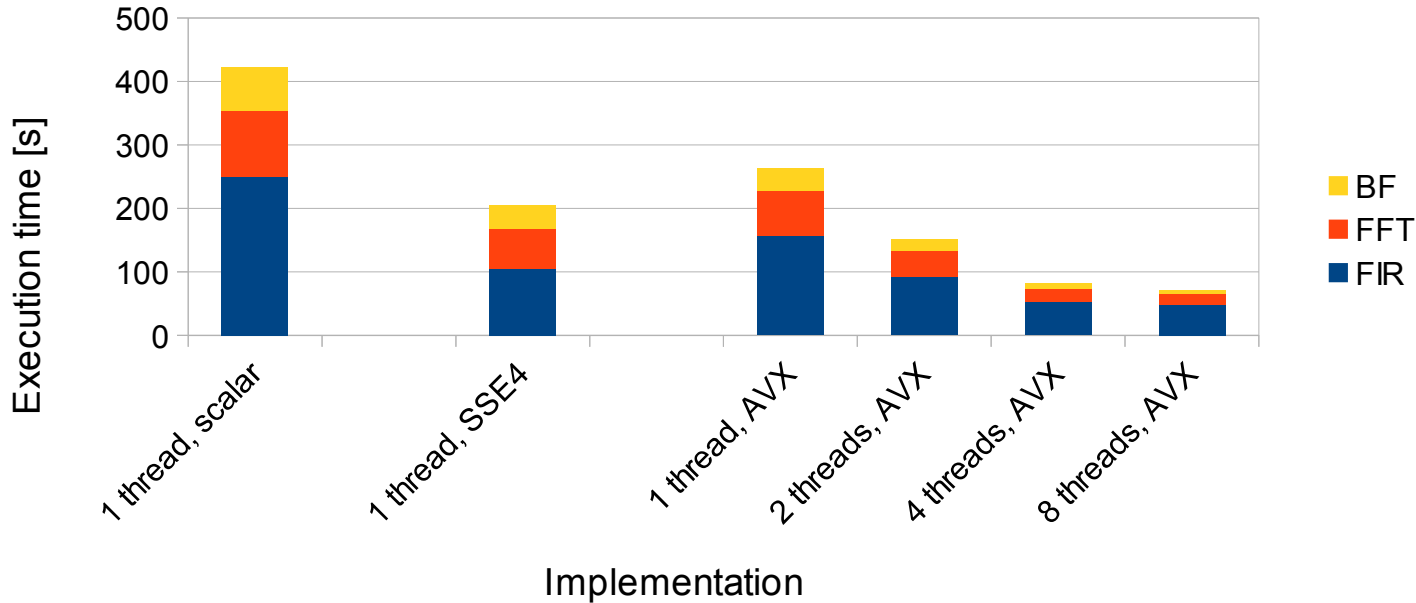
Block	Parameter	Requirement (32-bit FP)	Requirement (FPGA)
FIR	Compute	595.2 GFLOPs	595.2 GEOPs
	Antenna data in	71.5 GB/s	26.8 GB/s
	FIR data out	71.5 GB/s	44.7 GB/s
	Coefficients, delayed samples in/out	2.27 TB/s	992 GB/s
	Computational intensity	0.25 ops/byte	0.56 ops/byte
FFT	Compute	480 GFLOPs	480 GEOPs
	FIR data in	71.5 GB/s	44.7 GB/s
	FFT data out	71.5 GB/s	40.2 GB/s
	Twiddle factors	357.5 GB/s	178.8 GB/s
	Computational intensity	1.1 ops/byte	1.8 ops/byte
BF	Compute	74.2 GFLOPs	74.2 GEOPs
	FFT data in	34.6 GB/s	19.4 GB/s
	BF data out	739 MB/s	369.5 MB/s
	Calibration data	138.6 GB/s	69.3 GB/s
	Computational intensity	0.43 ops/byte	0.83 ops/byte
Total	Compute	1.1 TFLOPs	1.1 TEOPs
	Total data bandwidth	3.0 TB/s	1.4 TB/s
	Computational intensity	0.4 ops/byte	0.8 ops/byte

- Operational intensity: 59.9 ops/sample

Single CPU performance 55.5x below real-time

CPU performance of LOFAR station processing

Intel Core i7-3820, 1280 ms of antenna data



Performance compared to platform peak:

	GFLOPs	% of peak performance
1 thread, scalar	3.5	45.9 %
8 threads, AVX	20.7	9.0 %

- Single-threaded AVX implementation worse compared to SSE4
 - Different vectorization strategy required for scaling to multiple threads*

Roofline analysis

- Real-time station processing is done on 48 Xilinx Virtex-4 SX35 FPGAs
- Based on the roofline model, modern HW platforms require at least:
 - 3 Xilinx Virtex-7 x690T FPGAs
 - 56 Intel Core i7-3820 CPUs
 - 7 Nvidia Tesla K10 GPUs

- Sustaining full PCI-express 3.0 bandwidth, would require 4 Nvidia Tesla K10s

Available power measurements

- CPU and GPU: Measure power delivered by PDU
 - Full digital system measurements: both system idle and under load
 - Downside: consumption of unused peripherals
- GPU: Tesla's power measurement features
 - Only GPU power consumption
 - Downside: low time resolution
 - Downside: no host power consumption
- In-the-field FPGAs: Measure power consumption of digital boards
 - Full digital system measurement with little additional devices (idle and load)